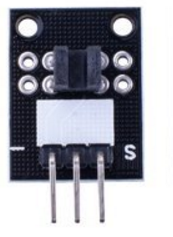
Light-Blocking Sensor  


Overview

A light-blocking sensor (also called a *photo interrupter*, and sometimes an *electric eye*) includes both a light emitter and light detector, separated by some channel of empty space. When the space is open (with nothing occupying it), the detector receives light from the emitter and electric current flows through the sensor’s internal transistor. When the channel is blocked by some object in or passing through it, the detector stops receiving light, and the electric switch opens. By measuring the transistor’s output, the Raspberry Pi can determine whether something is blocking the channel.

The light-blocking sensor in this experiment has a small onboard channel that can be interrupted by a slip of paper or a playing card. Light-blocking sensors of all sizes have tremendous applications in manufacturing, security, robotics, logistics, speedometry, odometry, etc.

In this experiment, the Raspberry Pi will report whether the light-blocking sensor’s channel is open or closed through an LED status indicator.

Experimental Materials

Raspberry Pi x1

Breadboard x1

Light-blocking sensor x1

LED (3-pin) x1

Resistor(330Ω) x1

Dupont jumper wires

Experimental Procedure

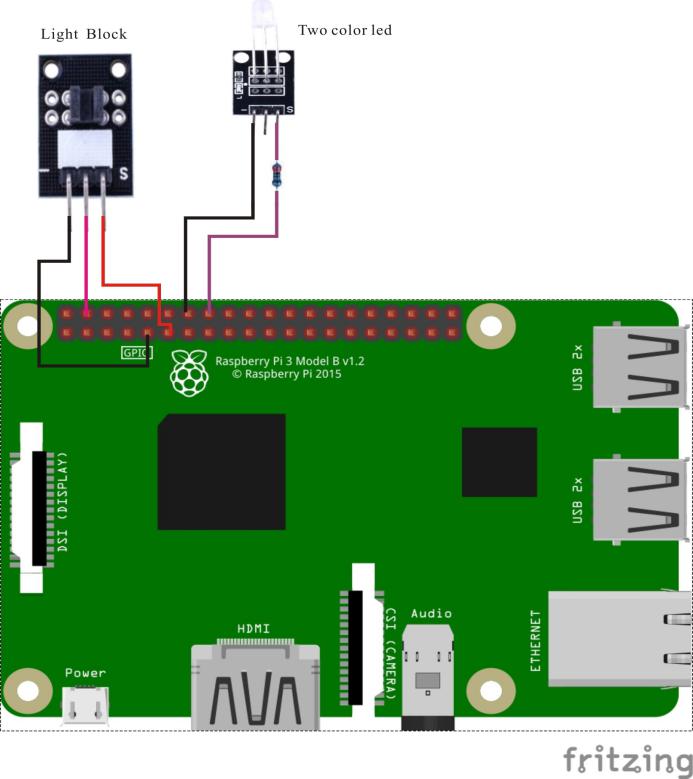
1. If you have not done so already, prepare your development system by installing the Python interpreter, RPi.GIO library, and wiringPi library as described in READ\_ME.TXT.
2. Install the light-blocking sensor and LED on your breadboard, and use Dupont jumper wires to connect them to each other and your Raspberry Pi as illustrated in the Wiring Diagram below. (The three-pin LED provided in this kit includes onboard series resistors, so no additional resistors are needed.)
3. Execute the sample code stored in this experiment’s subfolder.

If using C, compile and execute the C code:  
cd Code/C  
gcc lightBlock.c -o lightBlock.out –lwiringPi  
./ lightBlock.out

If using Python, launch the Python script:  
cd Code/Python  
python lightBlock.py

1. Make experimental observations while passing a piece of paper or light cardstock (a playing card or business card) between the two halves of the channel on the sensor. The code simply pushes the state of the sensor on to the state of the LED, so when you block the channel with a physical object, the LED illuminates.

Wiring Diagram



Light-blocking sensor pin position:

"S" ↔ Raspberry Pi pin 11

"+" ↔ Raspberry Pi +5V

"-" ↔ Raspberry Pi GND

LED pin position:

"S" ↔ Raspberry Pi pin 16

"-" ↔ Raspberry Pi GND

Sample Code

Python code

#!/usr/bin/env python

import RPi.GPIO as GPIO

import time

LightBreakPin = 11

LedPin = 16

def setup():

GPIO.setmode(GPIO.BOARD) # Numbers GPIOs by physical location

GPIO.setup(LedPin, GPIO.OUT) # Set LedPin's mode is output

GPIO.setup(LightBreakPin, GPIO.IN, pull\_up\_down=GPIO.PUD\_UP)

GPIO.output(LedPin, GPIO.LOW) # Set LedPin low to off led

def loop():

while True:

if(GPIO.input(LightBreakPin) == 0):

print 'Be covered....'

GPIO.output(LedPin, GPIO.HIGH)

else:

GPIO.output(LedPin, GPIO.LOW)

time.sleep(0.2)

def destroy():

GPIO.output(LedPin, GPIO.LOW) # led off

GPIO.cleanup() # Release resource

if \_\_name\_\_ == '\_\_main\_\_': # Program start from here

setup()

try:

loop()

except KeyboardInterrupt: # When 'Ctrl+C' is pressed, the child program destroy() will be executed.

destroy()

C code

#include <wiringPi.h>

#include <stdio.h>

#define LightBreakPin 0

#define LedPin 4

int main(void)

{

if(wiringPiSetup() == -1)

{

printf("setup wiringPi failed !");

return -1;

}

pinMode(LightBreakPin, INPUT);

pullUpDnControl(LightBreakPin, PUD\_UP);

pinMode(LedPin, OUTPUT);

while(1)

{

if(digitalRead(LightBreakPin) == LOW)

{

printf("Be covered....\n");

digitalWrite(LedPin, HIGH); //led on

}

else

{

digitalWrite(LedPin, LOW); //led off

}

}

return 0;

}